



# OPERATION MANUAL

## DIGIFORCE<sup>®</sup> 9311 PROFIBUS Integration into TIA Portal

© 2018 burster  
praezisionsmesstechnik gmbh & co kg  
Alle Rechte vorbehalten

Manufacturer:  
burster  
praezisionsmesstechnik gmbh & co kg  
Talstr. 1 - 5 P.O.Box 1432  
76593 Gernsbach 76587 Gernsbach  
Germany Germany

Valid from: **01.08.2018**  
Applies to: **DIGIFORCE<sup>®</sup> 9311-VXXX2**

Tel.: +49-7224-645-0  
Fax.: +49-7224-645-88  
Email: [info@burster.com](mailto:info@burster.com)  
[www.burster.com](http://www.burster.com)

2767-BA9311PRTIAEN-5770-071525

## Table of Contents

Introduction .....	3
1. Creating new project.....	4
2. Installation of GSD file .....	6
3. Creation of network connections .....	7
4. Create a sample program:.....	13
5. Further Examples .....	18
5.1 Reading and Writing of string data types.....	19
5.2 Retrieving of measurement results .....	22
5.3 Changing of window limits .....	25

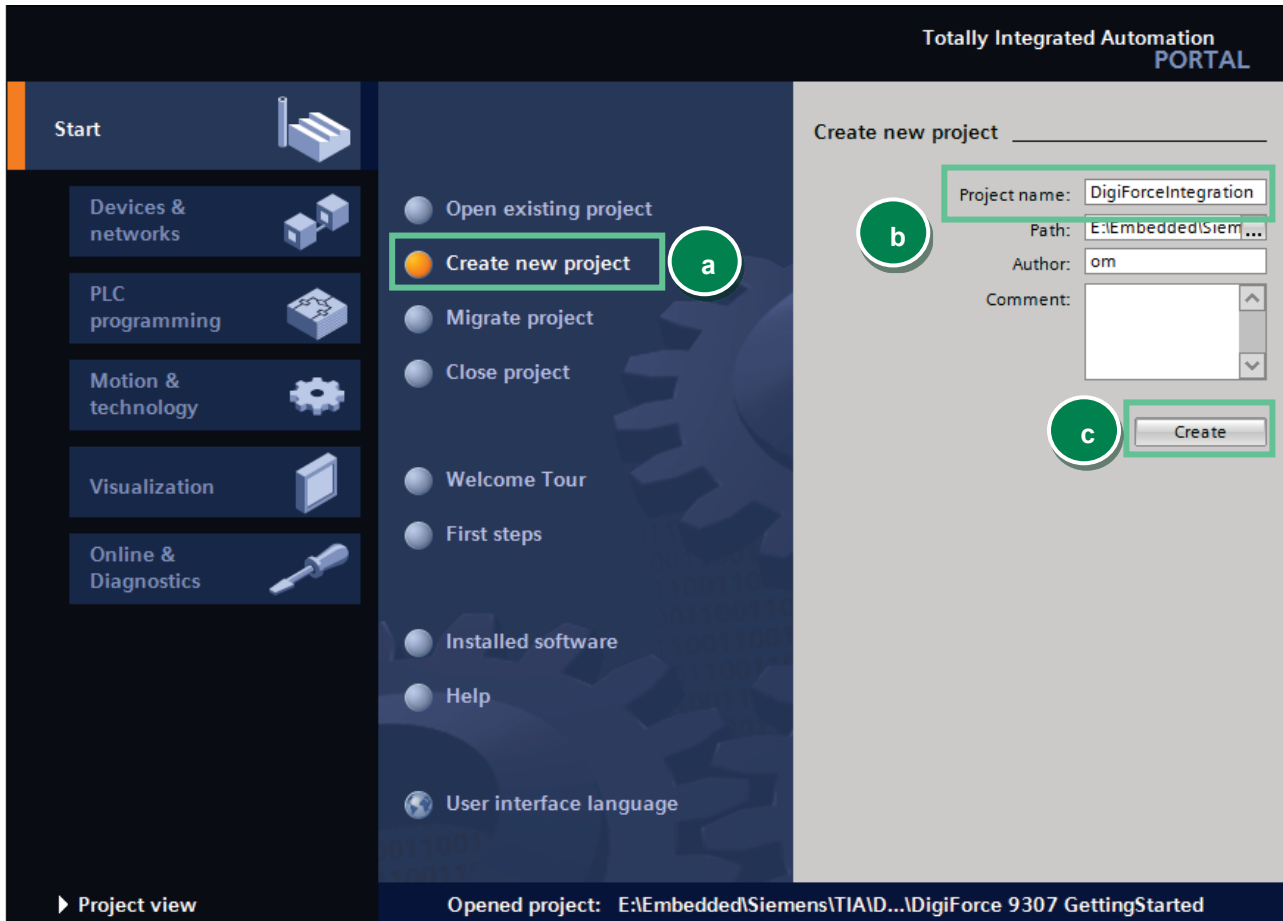
## Introduction

This quick start guide describes an approach how you can configure the DIGIFORCE<sup>®</sup> 9311 via TIA Portal using the example of S7-1511 CPU with a CM 1542-5 PROFIBUS Module. Please note that the samples here cannot be directly used in your production line because they have been extremely simplified to reach a better understanding. Therefore, you may have to complete them by checking of status, error, length values etc.

***Please also note that you will have to use the DIGIFORCE<sup>®</sup> 9311 PROFIBUS manual to get further information about input and output parameters (cyclic as well acyclic data transfer)***

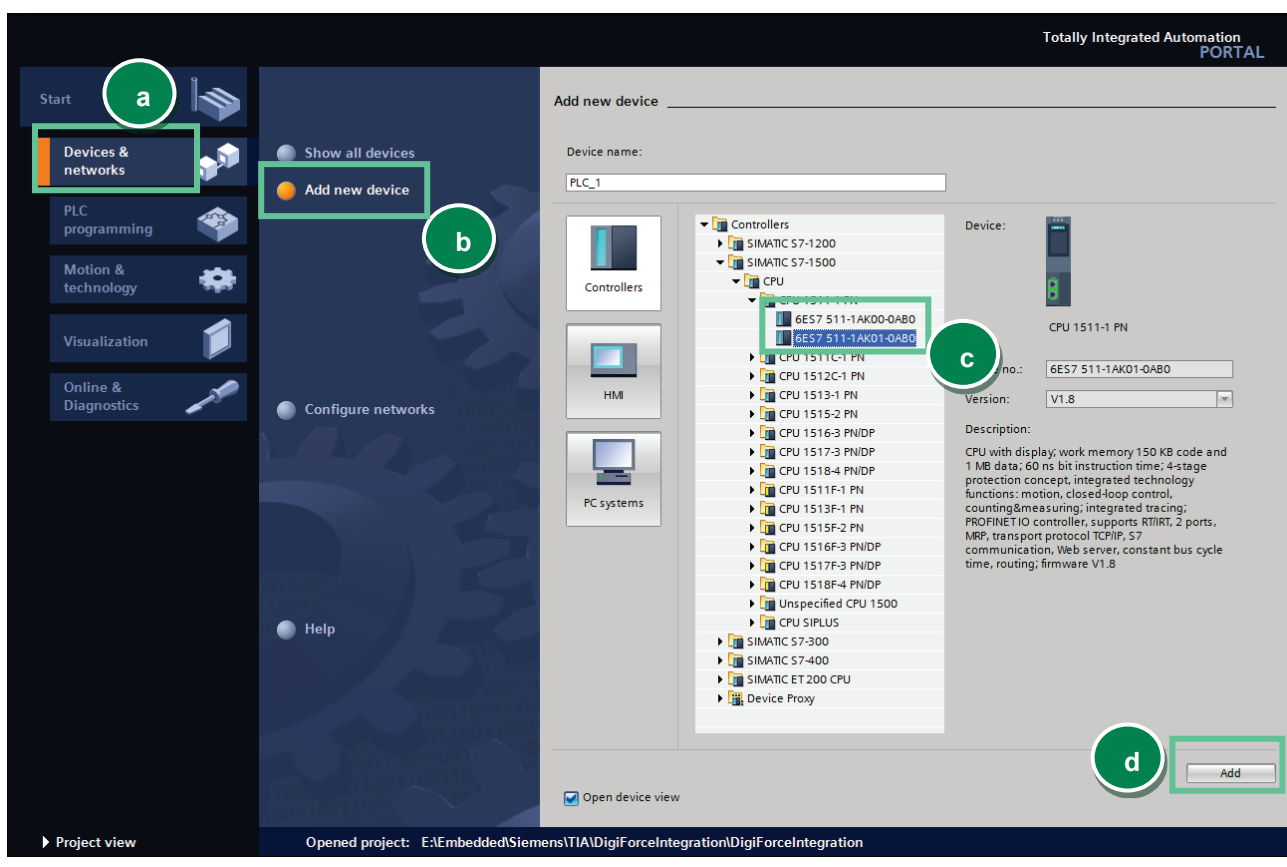
## 1. Creating new project

- Start the **Totally Integrated Automation Portal**, select **Create New Project** (a), assign the project a name (b) and click **Create** (c):



# DIGIFORCE<sup>®</sup> 9311 PROFIBUS

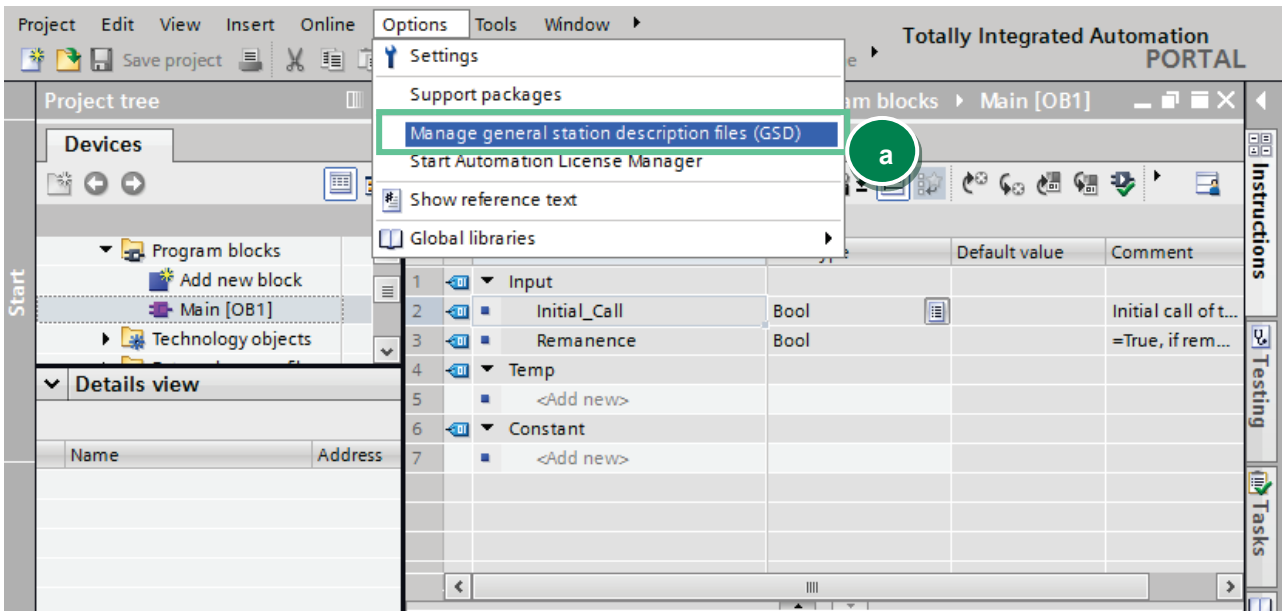
- Go to **Devices & networks** (a) on the left side select **Add new device** (b) and look for your CPU (c). Afterwards click the **Add** button (d).



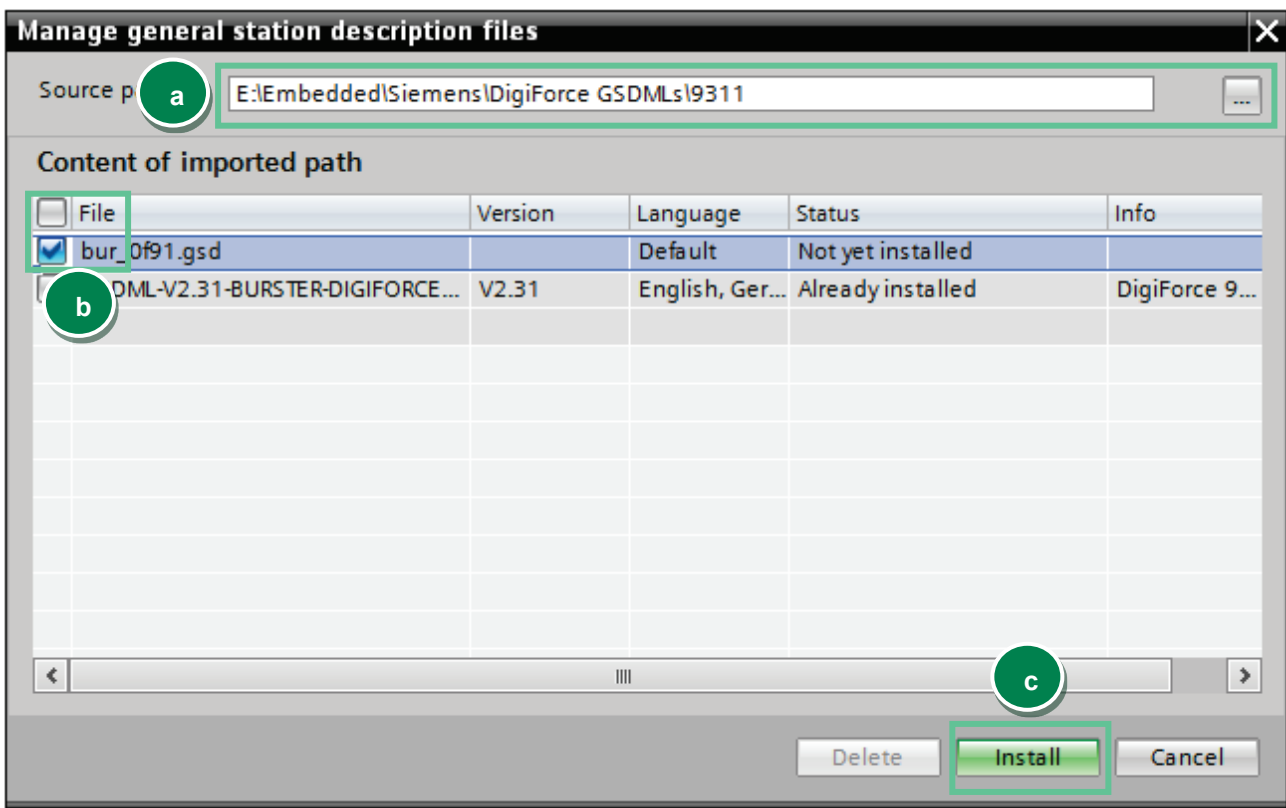
## 2. Installation of GSD file

**Note:** Please make sure that your GSD file is compatible to the field bus firmware in the DIGIFORCE® 9311. Also for compatibility reasons, uninstall all previous GSD files of particular device if you have any!

- Go to **Options->Manage general station description files (GSD)**

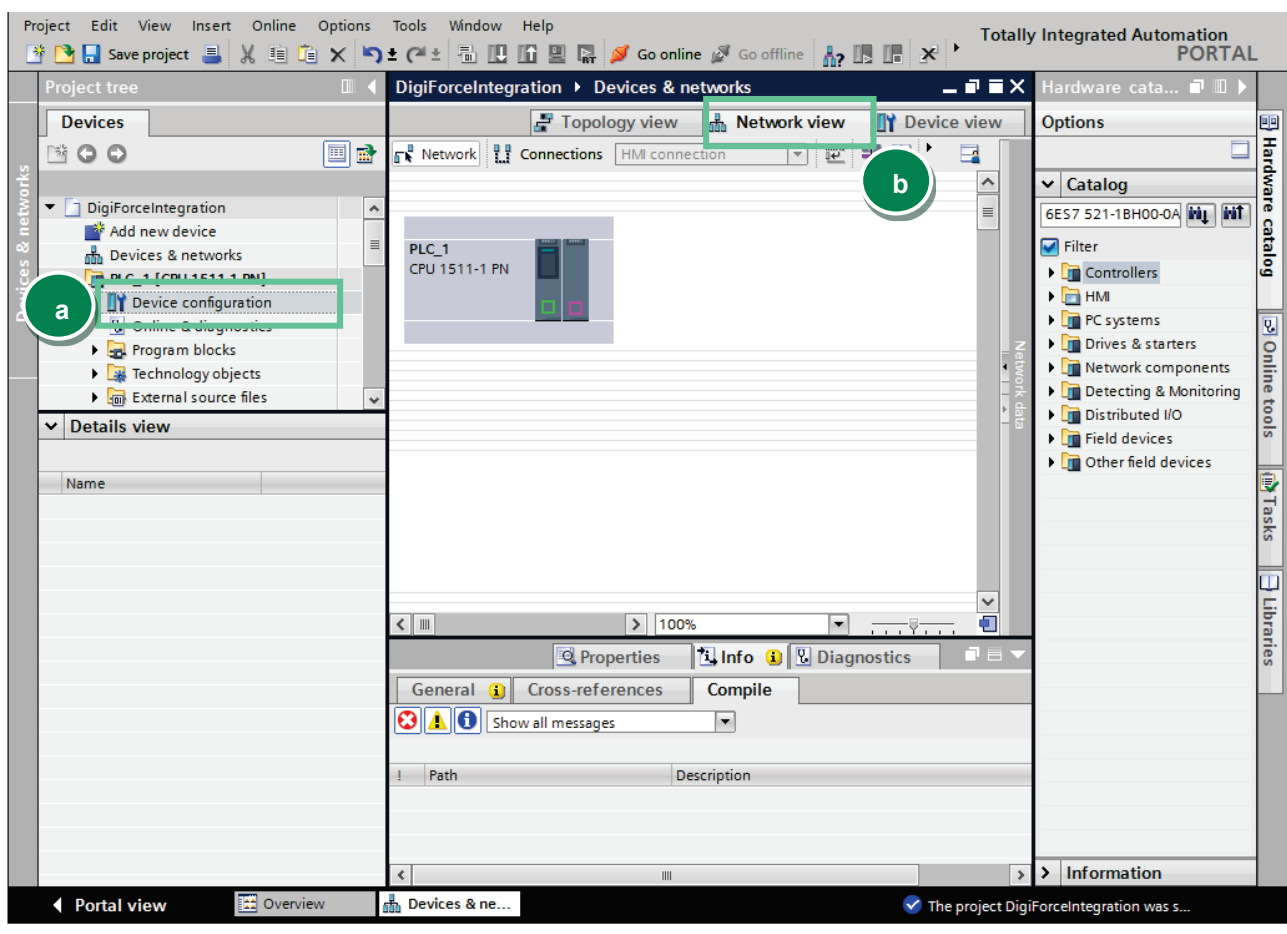


- Navigate to your DIGIFORCE® 9311 GSD directory (a)(you will find the GSD files on burster DVD that you got with your DIGIFORCE® 9311 device or on burster.com), select the GSD file (b) and click **Install** (c)

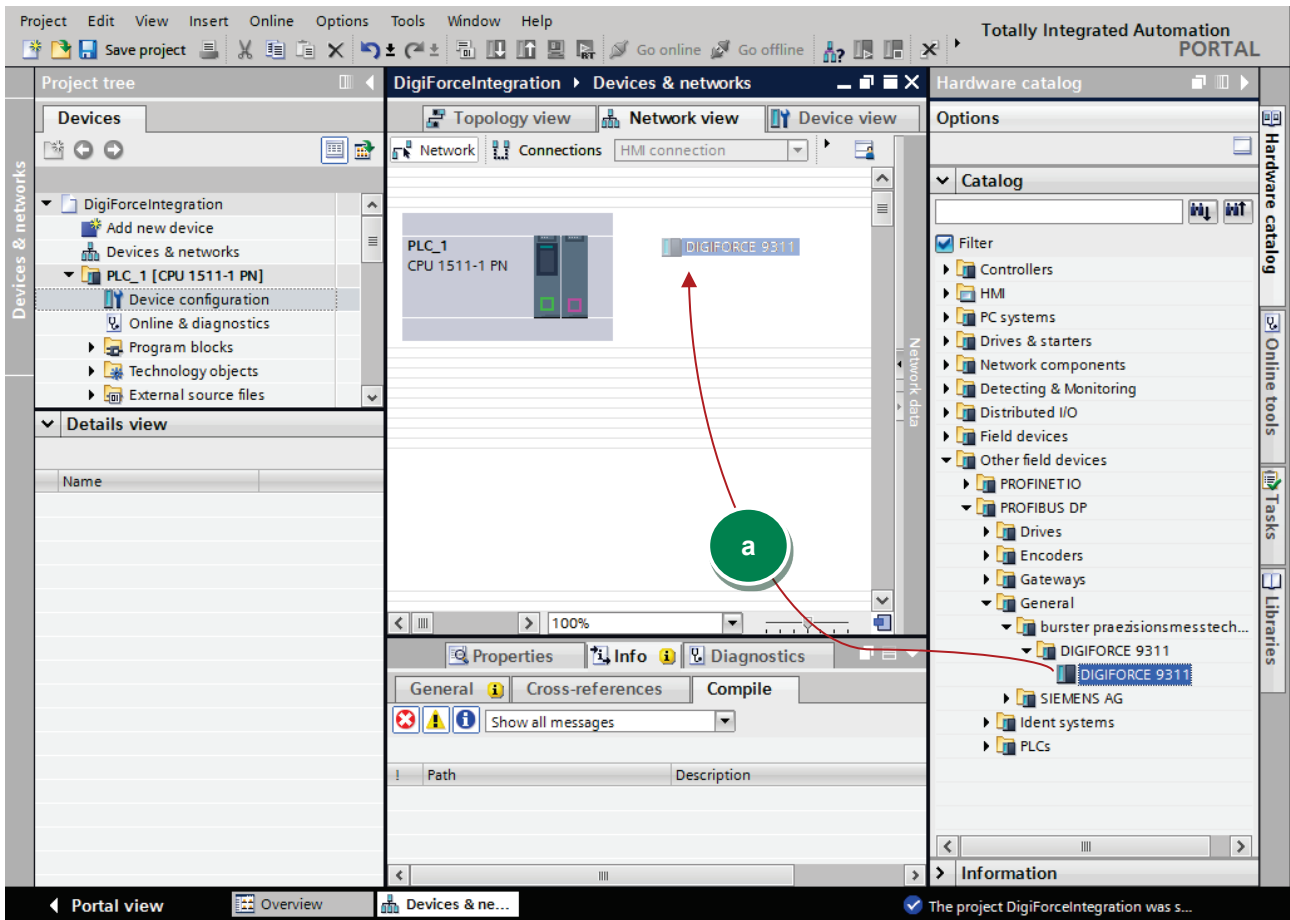


## 3. Creation of network connections

- Double click **Device Configuration** (a) in the project tree und switch to **Network view** (b) :



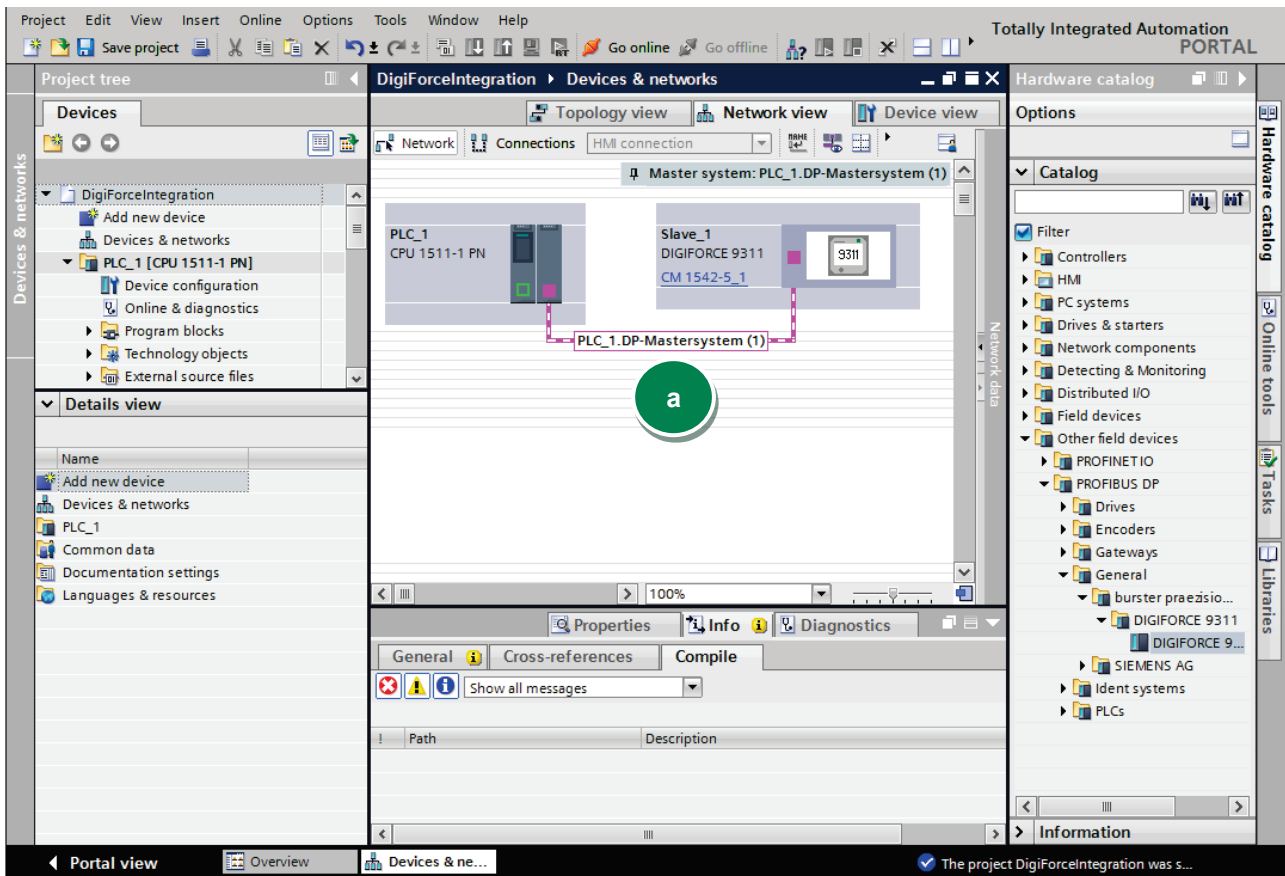
- Now select the DIGIFORCE<sup>®</sup> 9311 device in the catalog and drag & drop it into the working area (a):



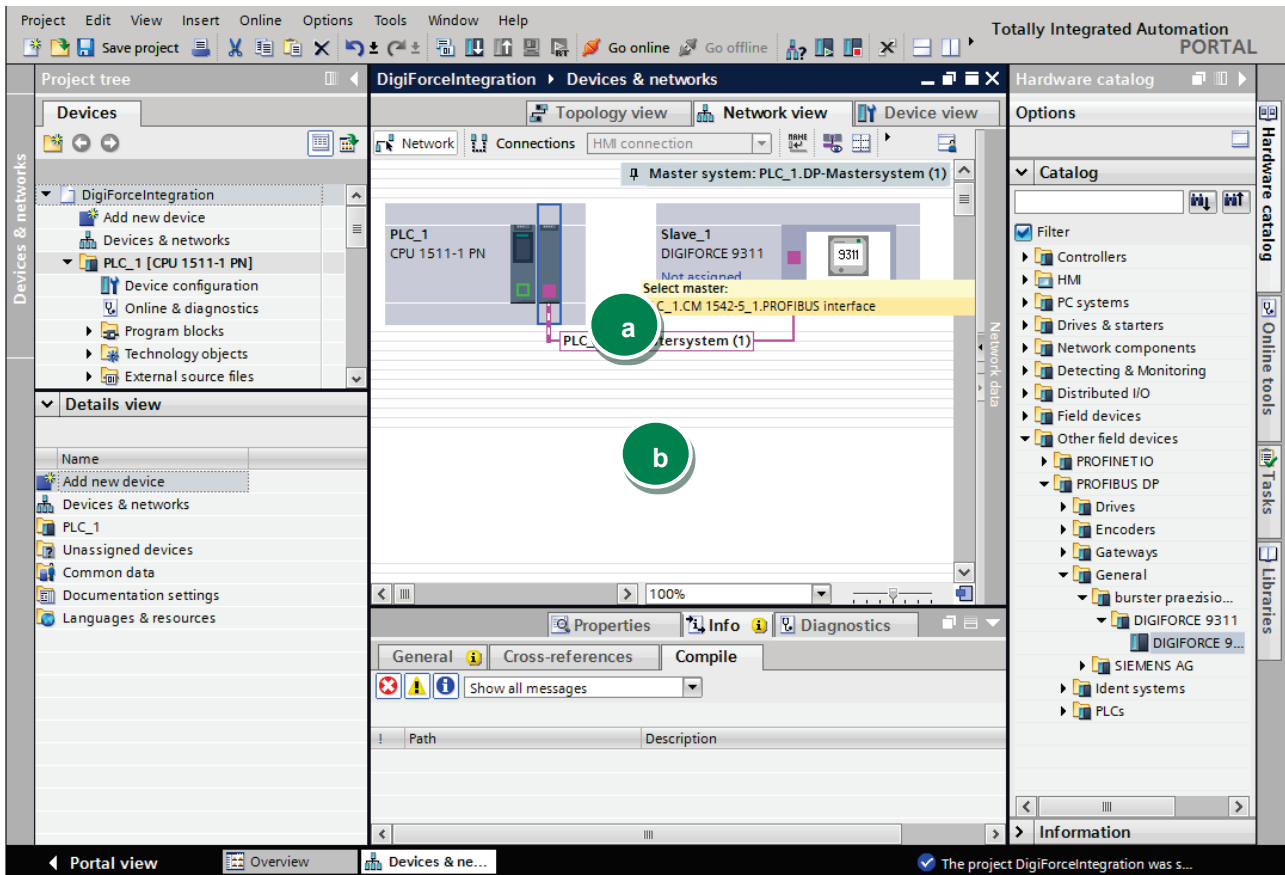


# DIGIFORCE® 9311 PROFIBUS

- Please select the port (pink rectangle) at the PROFIBUS module and hold the left mouse button down to connect the module with DIGIFORCE® 9311:

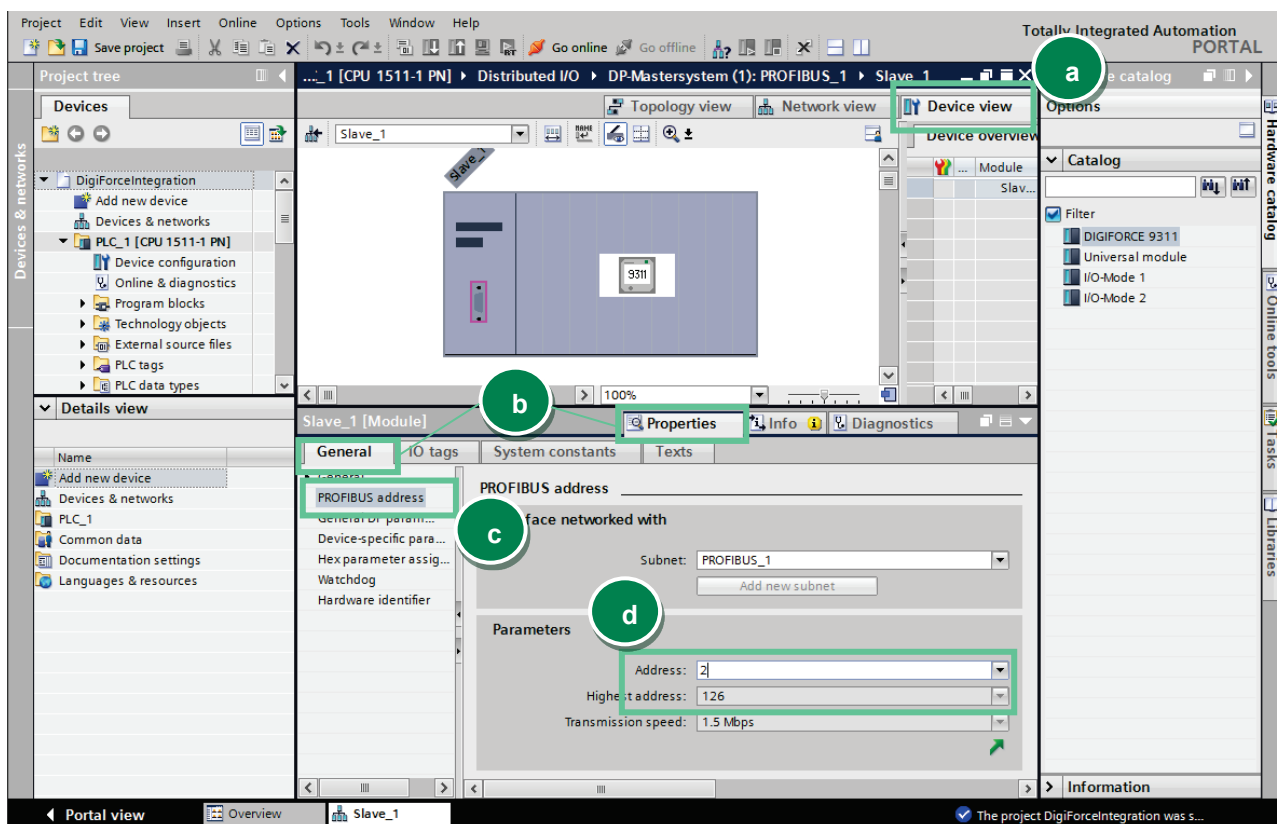


- If the DIGIFORCE<sup>®</sup> 9311 has **not** been automatically assigned to the master, click on the link “Not assigned” (a) of DIGIFORCE<sup>®</sup> 9311 and select your master (b):



# DIGIFORCE® 9311 PROFIBUS

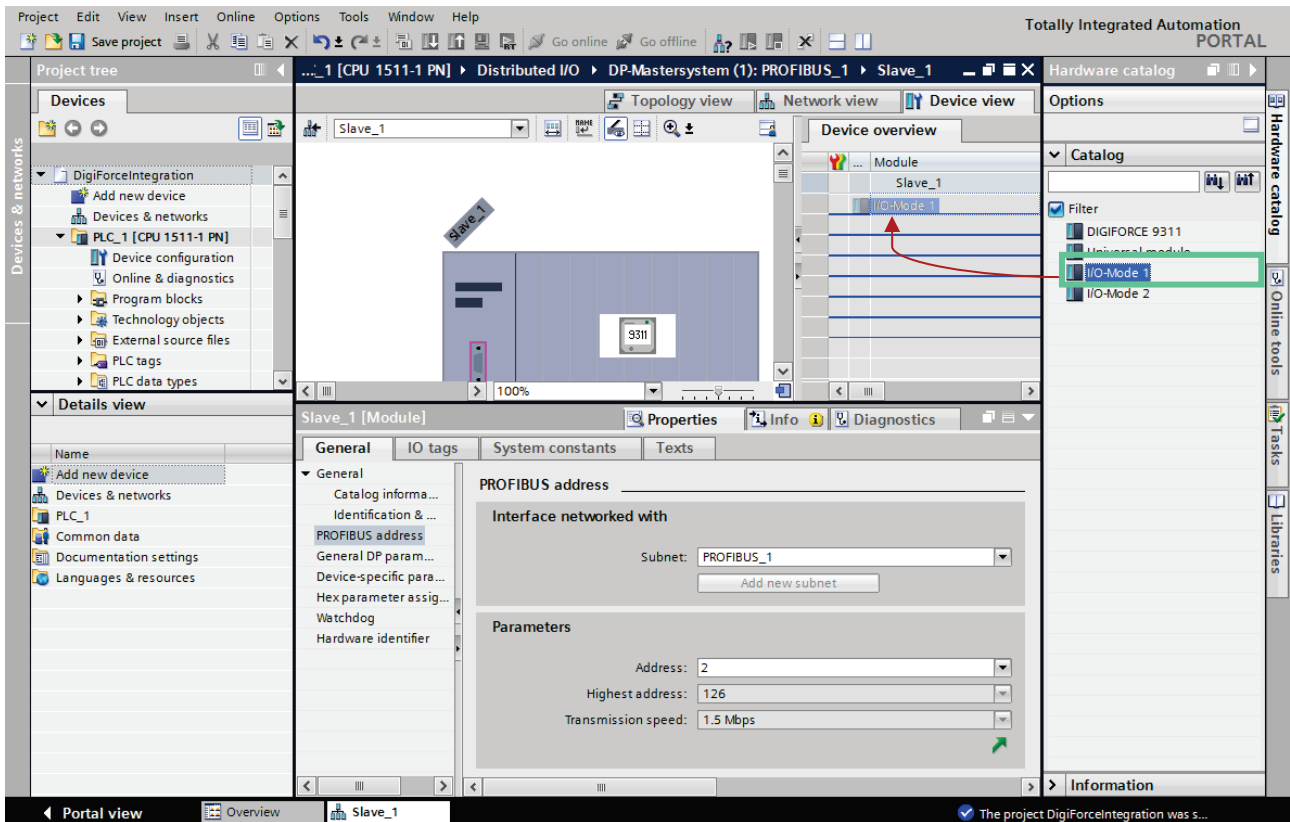
- Select the DIGIFORCE® 9311 device, goto **Device view** (a) and click the tabs **Properties** -> **General** (b). Finally select in the tree view on the left side **PROFIBUS address** (c) to see the assigned PROFIBUS address (d)



- Now you have to set this address in DIGIFORCE® 9311 device. You can do it over our pc configuration software DigiControl or directly in the device configuration menu **Basic setup->PROFIBUS->Station address:**

P 0	PROFIBUS	M54
SW-version	PB-V201600	
Serial number	01234567	
Control via	PLC	
Station address	2	
Cyclic data	----	

- To select the I/O-Mode 1<sup>1</sup> just drag the the I/O-Mode 1 entry from the hardware catalog into device overview table:

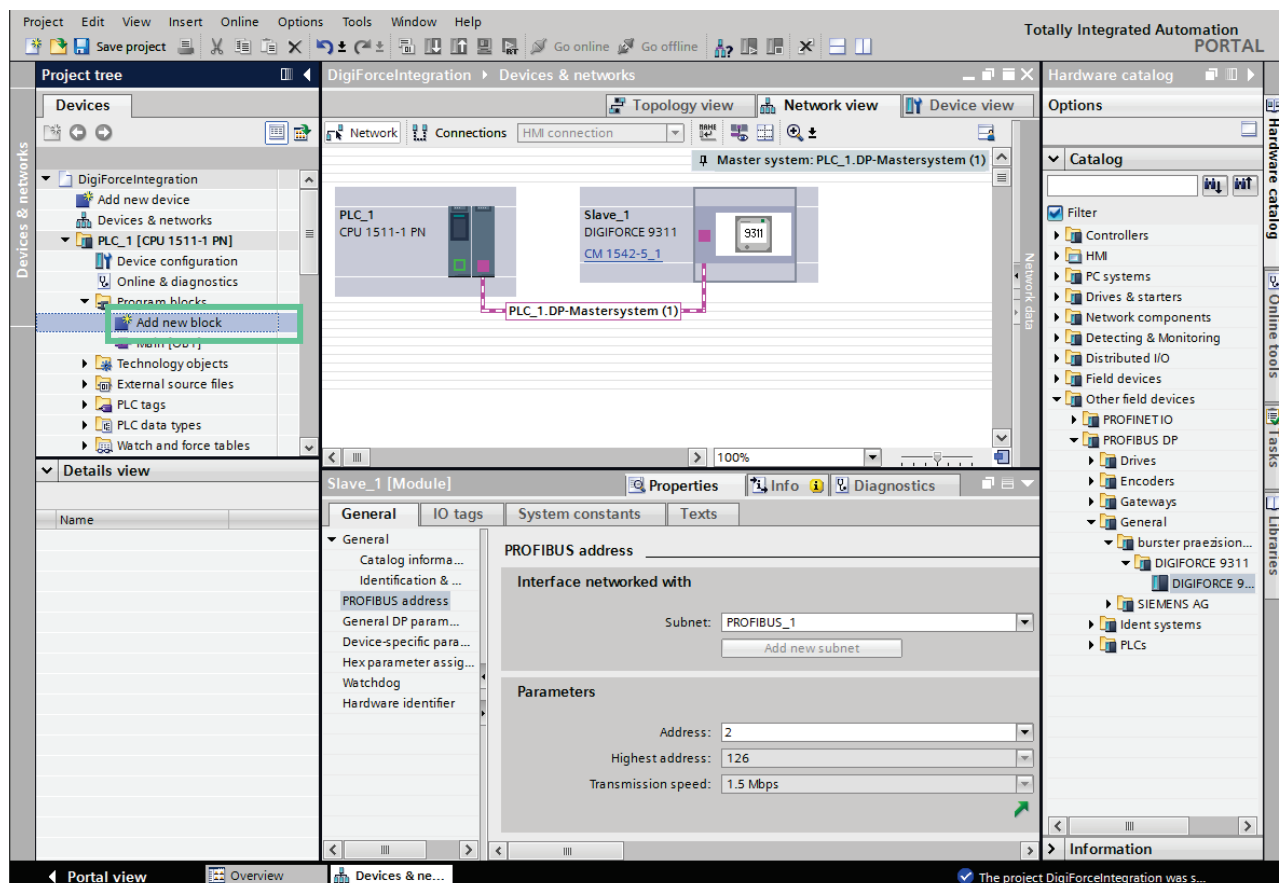


<sup>1</sup> Please refer to the section *Meaning of the content of the different protocol modes* of DIGIFORCE® 9311 PROFIBUS manual to get more information about available PROFIBUS DP-V0 Modes

## 4. Create a sample program:

In this section, you will learn how to create a simple program to start and stop a measurement periodically. You will need to refer to sections 6.2 PLC inputs and 6.3 PLC outputs of **DIGIFORCE® 9311 PROFIBUS** manual to understand the meaning of inputs and outputs bytes.

- Expand the tree node **Program blocks** in the Project tree and double click **Add new block**:



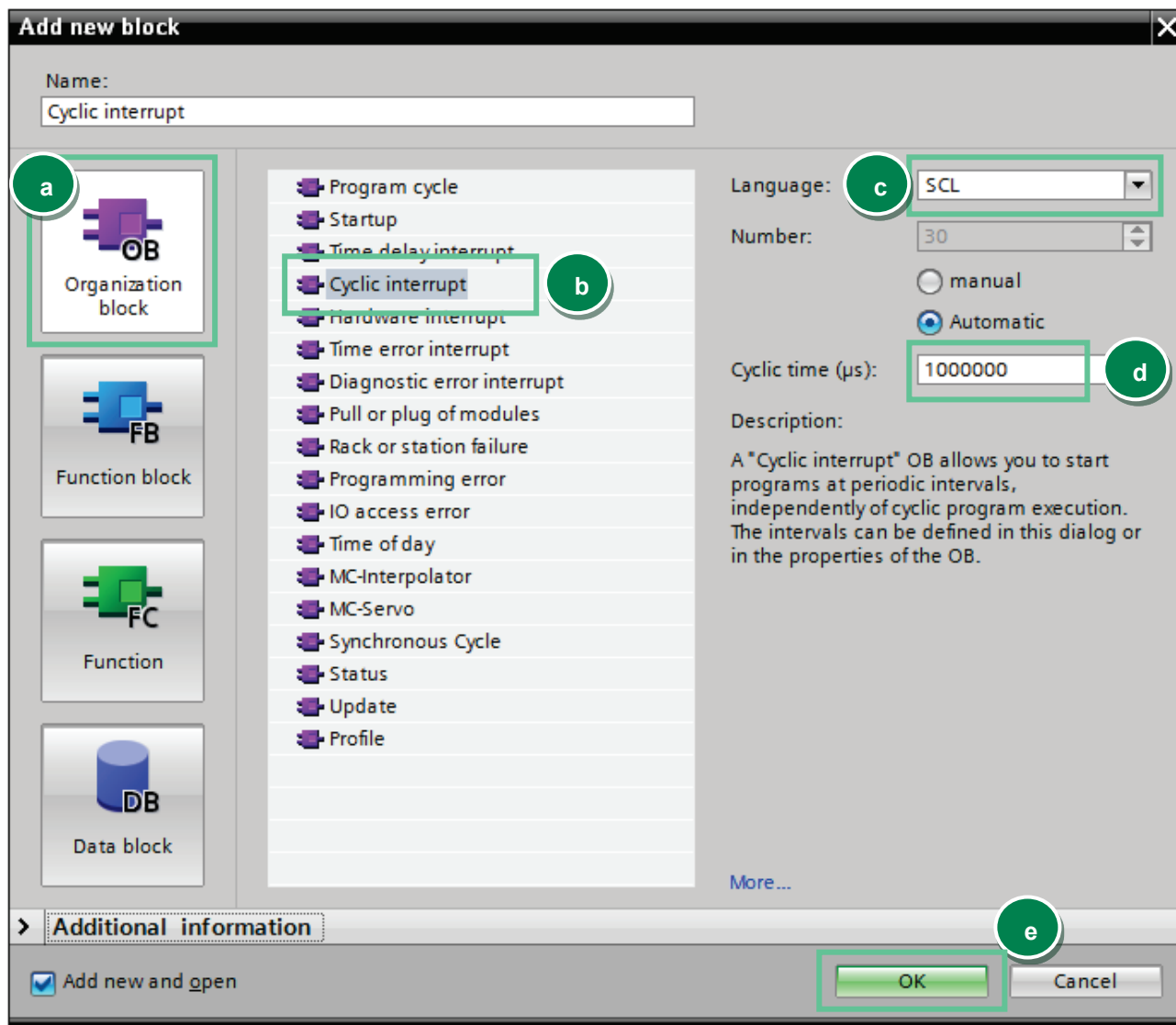
The screenshot displays the SIMATIC Manager software interface for configuring a PROFIBUS network. The main window shows a network topology with a master system (PLC\_1) and a slave system (Slave\_1). The slave system is identified as a DIGIFORCE 9311 module (CM 1542-5\_1) connected to the master system (PLC\_1-DP-Mastersystem (1)).

The **Details view** for the **Slave\_1 [Module]** is open, showing the **General** tab. The **PROFIBUS address** section is visible, with the following parameters:

- Interface networked with:** Subnet: PROFIBUS\_1
- Parameters:**
  - Address: 2
  - Highest address: 126
  - Transmission speed: 1.5 Mbps

The **Project tree** on the left shows the **Program blocks** folder expanded, with the **Add new block** option highlighted. The **Hardware catalog** on the right shows the **DIGIFORCE 9311** module selected.

- Select in the new window **Organization block** (a) and then **Cyclic interrupt** (b). As language set SCL (c), change the cyclic time to 1.000.000 µs (d) and click OK (e):



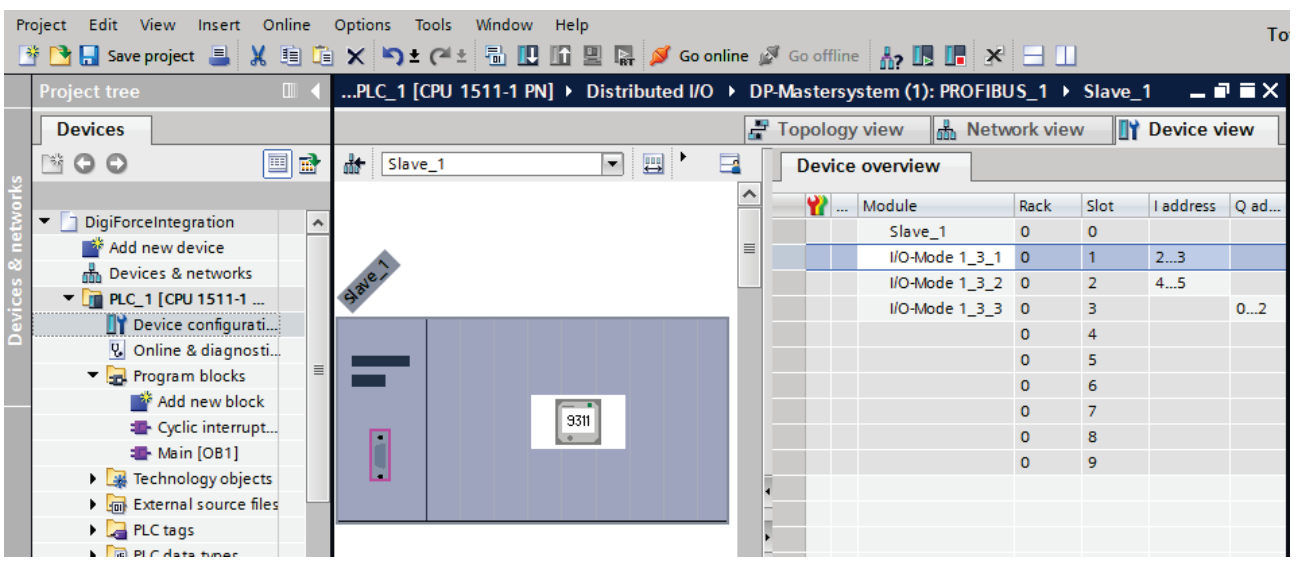
- Type in the following source code in the code field of the new block:

```

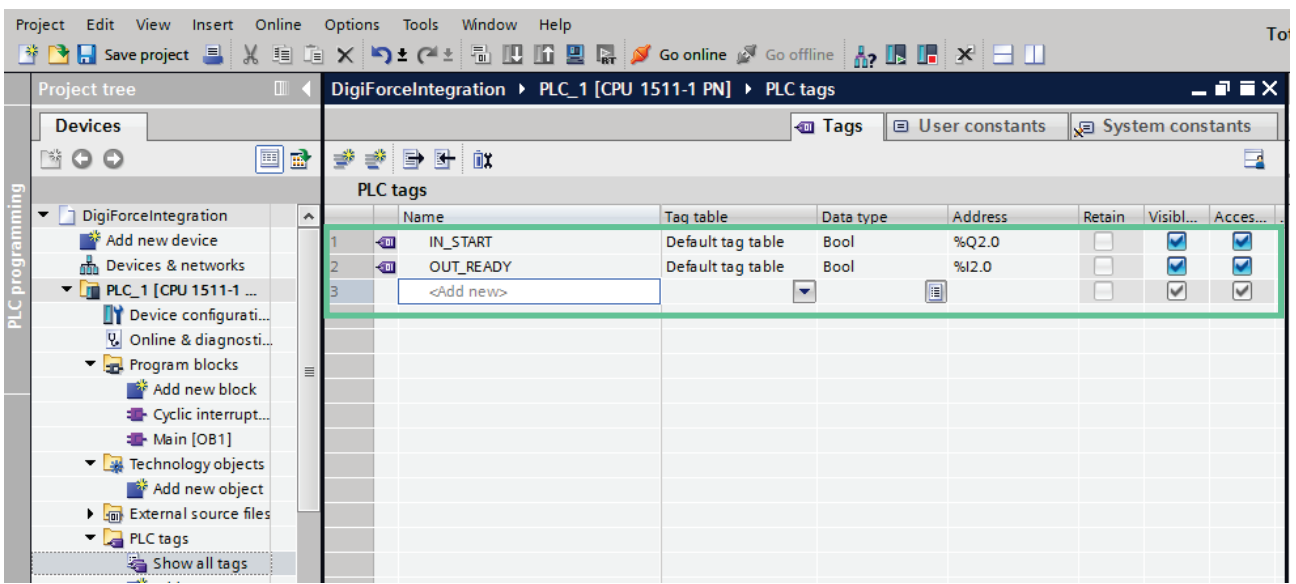
IF %Q2.0 = TRUE THEN // is IN_START (measurement start) set?
  %Q2.0 := FALSE; // IN_START (measurement start) is set, then reset it
ELSE // IN_START is not set
  IF %I2.0 = FALSE THEN // is OUT_READY (DIGIFORCE® 9311 ready for measurement) set?
    RETURN; // If not -> return
  END_IF; // Else
  %Q2.0 := TRUE; // set IN_START(measurement start)
END_IF;

```

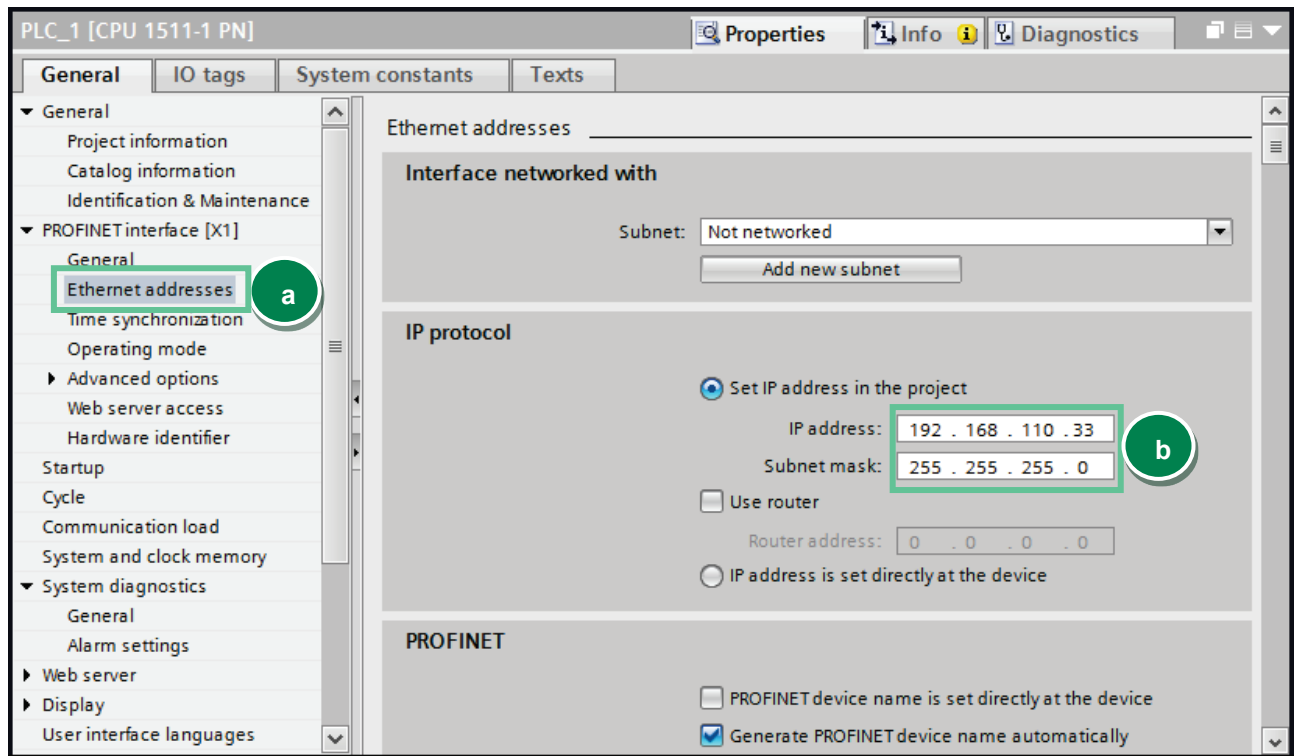
**Please note:** the addresses may be different. You have to check them in the **Device view->Device overview** of the DIGIFORCE<sup>®</sup> 9311



You will also see that the TIA-Editor replaces the input/output addresses with tags. You can change the tags names in PLC Tag table (e.g. to IN\_START and OUT\_READY):

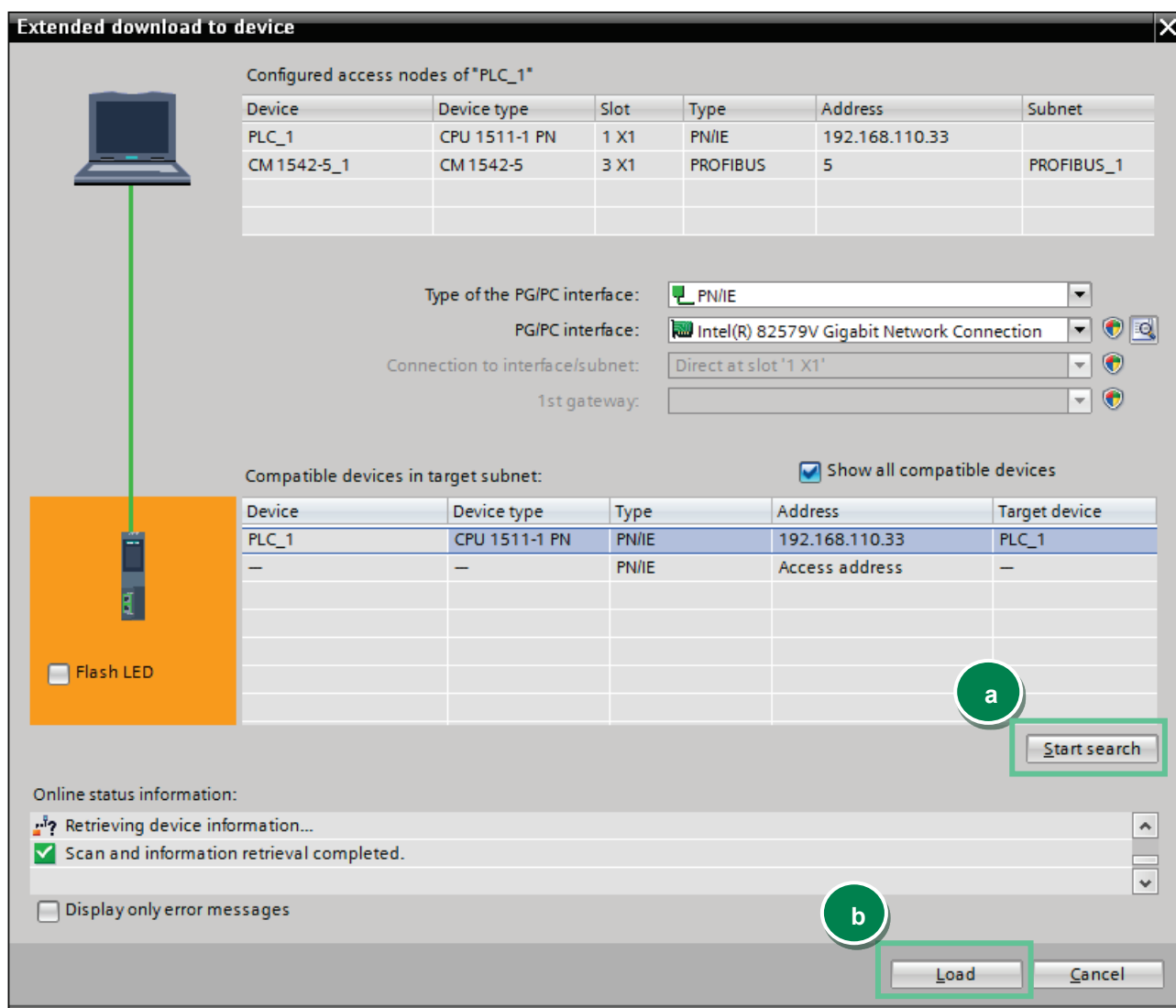


- Before you load the project into the CPU you have to set the IP address of your CPU. To do this please go to **Device view** and select **Ethernet addresses** (a) in **General** tab. Set now the IP-Address and a subnet mask(b) assigned to your in section **IP-Protocol**:





- To load the configuration into the CPU select it first go to **Online->Download to device** and click on **Start search** (a) to look for your controller. Then select the controller and click on **Load** (b):

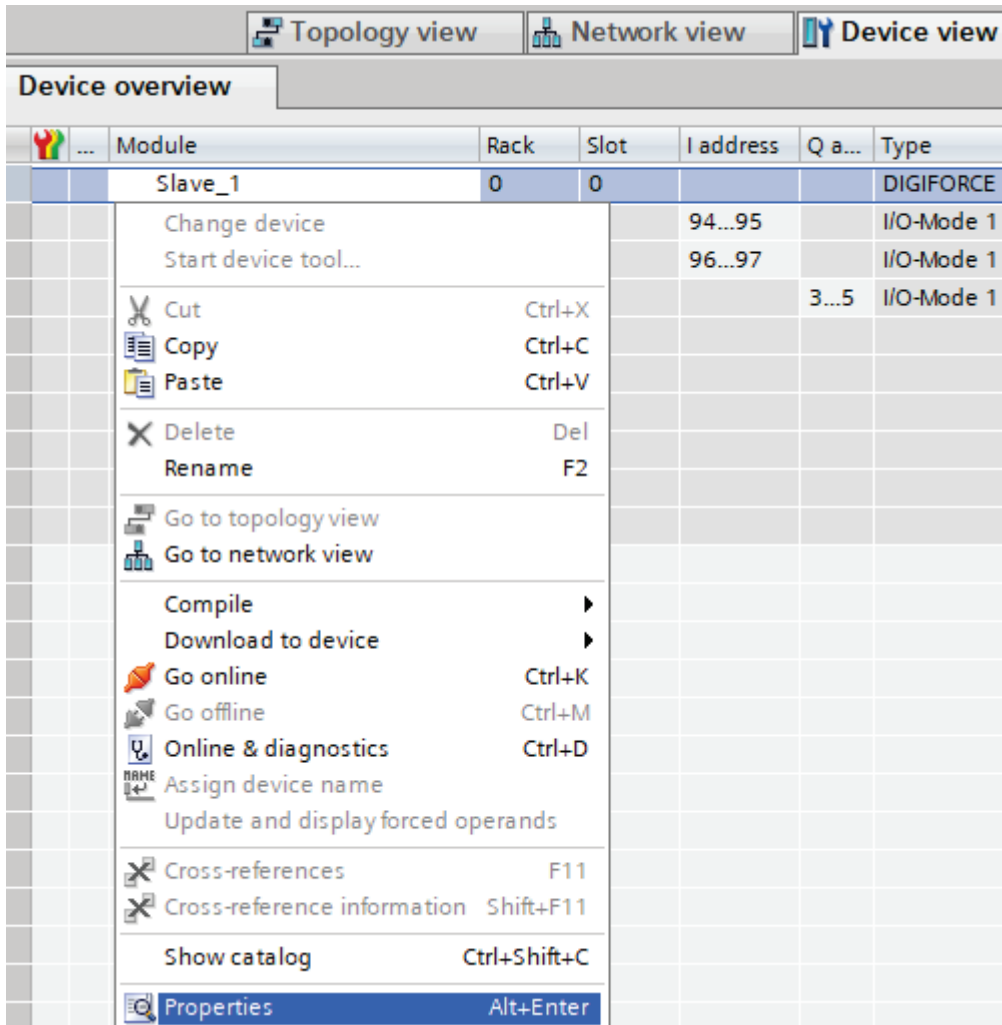


The DIGIFORCE<sup>®</sup> 9311 starts now a new measurement, waits a second, stops the measurement, waits a second and starts the measurement again and so on.

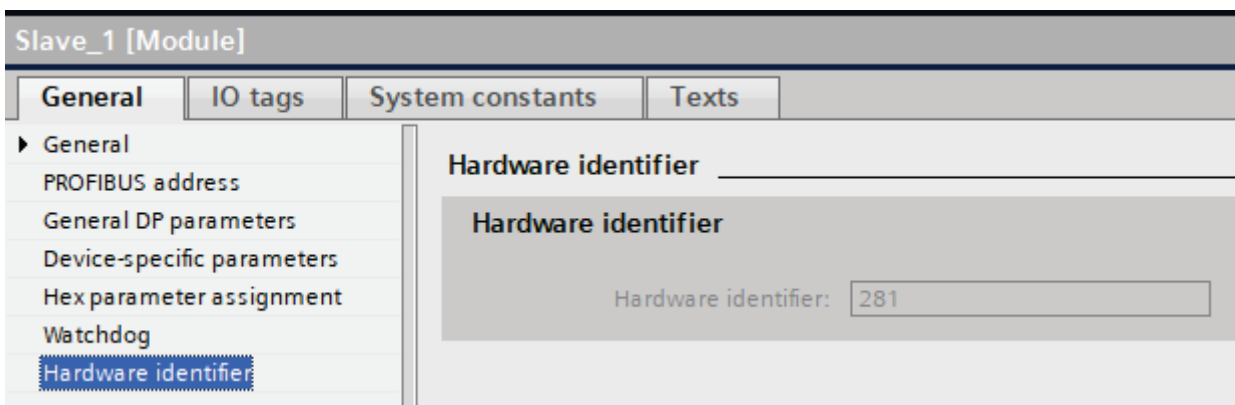
**Note:** Make sure that PROFIBUS Control is enabled in DIGIFORCE<sup>®</sup> 9311. For details, see chapter 3.5 *Configuration menu in DIGIFORCE<sup>®</sup> 9311* of **DIGIFORCE<sup>®</sup> 9311 PROFIBUS** manual.

## 5. Further Examples

In the followed examples, a *Hardware-ID* is used to access a certain slot. To find this, please select a DIGIFORCE® 9311 device in **Topology view** or **Network view** and then switch to **Device view**. Click with the right mouse button on the Slave module and select **Properties**:



You will see the hardware identifier in the tab **General**:



## 5.1 Reading and Writing of string data types

In this example, we perform an indirect read access on slot 30/Subslot 1/index 10 to get the device type of DIGIFORCE® 9311 and then we will set the first nine characters of this string as DIGIFORCE® 9311 station name on Slot 30/Subslot 1/Index 17. For these acyclic operations, you will need an instance of RDREC und WRREC blocks. You can see the new station name in the **info menu** of DIGIFORCE® 9311.

### PLC parameters table:

	Name	Data type	Default value	Comment
4	Temp			
5	Busy	Bool		
6	Done	Bool		
7	Valid	Bool		
8	Error	Bool		
9	Status	DWord		
10	data	Array[0..18] of Byte		
11	lenRead	UInt		
12	Constant			

### Sourcecode:

```
#data[0] := 0; // Byte 0 of slot number to access
#data[1] := 30; // Byte 1 of slot number to access

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 1,         // Index 1: Slot number for indirect addressing
    LEN := 2,           // Length of data to write
    DONE => #Done,      // Write done
    BUSY => #Busy,       // Write not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    RECORD := #data);  // Write the the slot number that must be accessed
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
  RETURN;
END_IF;

REPEAT
  "RDREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 1,         // Index 1
    MLEN := 2,          // Max. lenth of data to read
    VALID => #Valid,    // New Data Received and valid
    BUSY => #Busy,       // Read not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    LEN => #lenRead,    // Number of bytes was read from device
    RECORD := #data);  // Read the current slot number from DIGIFORCE® 9311

UNTIL NOT #Busy AND #data[1] <> 0 AND #data[0] <> 30 // Wait till the DIGIFORCE® 9311 confirmed the slot
number
END_REPEAT;
```

```

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
RETURN;
END_IF;

REPEAT
  "RDREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 10,        // Read from index 10: Device Detection
    MLEN := 18,         // Max. lenh of data to read
    VALID => #Valid,    // New Data Received and valid
    BUSY => #Busy,      // Read not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    LEN => #lenRead,    // Number of bytes was read from device
    RECORD := #data);   // Read data from slot 30 index 10
UNTIL NOT #Busy
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
RETURN;
END_IF;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1(see introduction of 'Further examples')
    INDEX := 17,        // Slot 30, Index 17: station name
    LEN := 9,           // Lenth of data to write
    DONE => #Done,      // Write done
    BUSY => #Busy,      // Write not completed yet
    ERROR => #Error,    // Error
    STATUS => #Status,  // State
    RECORD := #data);   // Write data has been read from index 10 to index 17
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
RETURN;
END_IF;

```

**Example 2:** Writing of serial number SN1 into device order sheet

**Note:** Datatype **String** in TIA Portal contains two additional bytes, which represent the length of the string. To avoid these two bytes being sent use the function 'Strg\_TO\_Chars' to convert the String to a byte array as shown below:

**PLC parameters table:**

Name	Data type	Default value
serial	String	
bytesWritten	UInt	
serialAsByteArray	Array[0..64] of Byte	

data	Array[0..18] of Byte	
Valid	Bool	
Done	Bool	
Status	DWord	
Busy	Bool	
Error	Bool	
lenRead	UInt	

## Sourcecode:

```
#serial := 'SN123456789';
#data[0] := 0; // Byte 0 of slot number to access
#data[1] := 30; // Byte 1 of slot number to access

Strg_TO_Chars(Strg:= #serial,           // Serial as String
              pChars:= 0,              // Position in serialAsByteArray
              Cnt => #bytesWritten,    // Number of Bytes have been written to serialAsByteArray
              Chars:= #serialAsByteArray);

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 1,        // Index 1: Slot number for indirect addressing
    LEN := 2,          // Length of data to write
    DONE => #Done,    // Write done
    BUSY => #Busy,    // Write not completed yet
    ERROR => #Error,  // Error
    STATUS => #Status, // State
    RECORD := #data); // Write the the slot number that must be accessed
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
  RETURN;
END_IF;

REPEAT
  "RDREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 1,        // Index 1
    MLEN := 2,         // Max. lenth of data to read
    VALID => #Valid,   // New Data Received and valid
    BUSY => #Busy,    // Read not completed yet
    ERROR => #Error,  // Error
    STATUS => #Status, // State
    LEN => #lenRead,  // Number of bytes was read from device
    RECORD := #data); // Read the current slot number from DIGIFORCE® 9311

UNTIL NOT #Busy AND #data[1] <> 0 AND #data[0] <> 30 // Wait till the DIGIFORCE® 9311 confirmed the slot
number
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
  RETURN;
END_IF;
```

## REPEAT

```
"WRREC_DB"(REQ := TRUE,
  ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
  INDEX := 65,        // Index 65: Order sheet - Serial number 1
  LEN := INT_TO_UINT(LEN(#serial)), // Length of serial
  DONE => #Done,      // Write done
  BUSY => #Busy,      // Write not completed yet
  ERROR => #Error,    // Error
  STATUS => #Status,  // State
  RECORD := #serialAsByteArray);
```

**UNTIL NOT #Busy AND #Done**

**END\_REPEAT;**

## 5.2 Retrieving of measurement results

This example shows you how to read the first max. 200 X-Coordinates of the current curve.

### PLC parameters tables:

4	Temp		
5	Valid	Bool	
6	Done	Bool	
7	Busy	Bool	
8	Error	Bool	
9	Status	DWord	
10	data	Array[0..18] of Byte	
11	i	Int	
12	lastIndex	UInt	
13	lenRead	UInt	

		DATA		
		Name	Data type	Start value
DigiForceIntegration		1 Static		
Add new device		2 coordinates	Array[0..200] of Real	
Devices & networks		3 coordinates[0]	Real	0.0
PLC_1 [CPU 1511-1 PN]		4 coordinates[1]	Real	0.0
Device configuration		5 coordinates[2]	Real	0.0
Online & diagnostics		6 coordinates[3]	Real	0.0
Program blocks		7 coordinates[4]	Real	0.0
Add new block		8 coordinates[5]	Real	0.0
Cyclic interrupt [OB30]		9 coordinates[6]	Real	0.0
Main [OB1]		10 coordinates[7]	Real	0.0
Startup [OB100]		11 coordinates[8]	Real	0.0
DATA [DB3]				

### Sourcecode:

```
#data[0] := 0;           // Byte 0 of slot number to access
#data[1] := 104;        // Byte 1 of slot number to access

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
```

```

INDEX := 1, // Index 1: Slot number for indirect addressing
LEN := 2, // Length of data to write
DONE => #Done, // Write done
BUSY => #Busy, // Write not completed yet
ERROR => #Error, // Error
STATUS => #Status, // State
RECORD := #data); // Write the the slot number that must be accessed
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := // Check Status and Error
24) <> 0 THEN
RETURN;
END_IF;

REPEAT
"RDREC_DB"(REQ := TRUE, // HW-ID of Slot 1 (see introduction of 'Further examples')
ID := 281, // Index 1
INDEX := 1,
MLEN := 2, // Max. length of data to read
VALID => #Valid, // New Data Received and valid
BUSY => #Busy, // Read not completed yet
ERROR => #Error, // Error
STATUS => #Status, // State
LEN => #lenRead, // Number of bytes was read from device
RECORD := #data); // Read the current slot number from DIGIFORCE® 9311

UNTIL NOT #Busy AND #data[1] <> 0 AND // Wait till the DIGIFORCE® 9311 confirmed the slot number
#data[0] <> 104
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := // Check Status and Error
24) <> 0 THEN
RETURN;
END_IF;

REPEAT
"WRREC_DB"(REQ := TRUE, // Write access to index 10 to prepare the curve
ID := 281, // Hardware-ID of slot 1 (see introduction of 'Further
INDEX := 10, // examples')
LEN := 2, // Index
DONE => #Done, // Length in bytes to write
BUSY => #Busy,
ERROR => #Error,
STATUS => #Status,
RECORD := #data);

UNTIL NOT #Busy AND #Done // Command-Code to prepare the curve (any two bytes)
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := // Check Status and Error
24) <> 0 THEN
RETURN;
END_IF;

REPEAT
"RDREC_DB"(REQ := TRUE,
ID := 281,
INDEX := 10, // Read the number of curve values
MLEN := 2, // Hardware-ID of Slot 1

```

```

VALID => #Valid, // Index
BUSY => #Busy, // Max. length to read
ERROR => #Error,
STATUS => #Status,
LEN => #lenRead,
RECORD := #lastIndex); // Number of bytes read
UNTIL NOT #Busy // Number of values in the curve - 1
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N :=
24) <> 0 OR #lenRead <> 2 OR #lastIndex = 0 // If read failed -> return
THEN
RETURN;
END_IF;

#data[0] := 0; // Byte 0 of coordinate group number
#data[1] := 0; // Byte 1 of coordinate group number

REPEAT
"WRREC_DB"(REQ := TRUE, // Write access to to set the coord. group number
ID := 281, // Hardware-ID of slot 1
INDEX := 19, // Index 19: Coordinate group number
LEN := 2, // Length in bytes to write
DONE => #Done,
BUSY => #Busy,
ERROR => #Error,
STATUS => #Status,
RECORD := #data); // Coordinate group number
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N :=
24) <> 0 THEN // Check Status and Error
RETURN;
END_IF;

REPEAT
"RDREC_DB"(REQ := TRUE,
ID := 281, // HW-ID of Slot 1 (see introduction of 'Further examples')
INDEX := 19, // Index 19: Coordinate group number
MLEN := 2, // Max. length of data to read
VALID => #Valid,
BUSY => #Busy,
ERROR => #Error, // Error
STATUS => #Status, // State
LEN => #lenRead, // Number of bytes was read from device
RECORD := #data); // Read the current slot number from DIGIFORCE® 9311

UNTIL NOT #Busy AND #data[1] = 0 AND // Wait till the DIGIFORCE® 9311 confirmed the selected
#data[0] = 0 group number
END_REPEAT;

// Check Status and Error
IF #Error = TRUE OR SHR(IN := #Status, N :=
24) <> 0 THEN
RETURN;
END_IF;

// Read the coordinates
FOR #i := 0 TO UINT_TO_INT(#lastIndex - 1)
DO // Read access to read out a curve coordinates
REPEAT // Hardware-ID of slot 1

```



```

"RDREC_DB"(REQ := TRUE, // Index from which a coordinate should be read
  ID := 281, // Max. length to read
  INDEX := #i + 20,
  MLEN := 4,
  VALID => #Valid,
  BUSY => #Busy,
  ERROR => #Error, // Number of bytes read
  STATUS => #Status, // Array to store the read coordinates
  LEN => #lenRead,
  RECORD := "DATA".coordinates[#i]);
UNTIL NOT #Busy
END_REPEAT; // Check Status and Error

IF #Error = TRUE OR SHR(IN := #Status, N :=
24) <> 0 OR #lenRead < 4 THEN
  RETURN;
END_IF;
END_FOR;

```

## 5.3 Changing of window limits

This example shows you how to enable Evaluation Window 1 and set its coordinates.

**Note:** You have to write all four window limits and then confirm them with index 15. It is not possible to change only one single limit, e.g. xMax.

**PLC parameters table:**

Name	Data type	Default value
Temp		
data	Array[0..2] of Byte	
Valid	Bool	
Done	Bool	
Status	DWord	
Busy	Bool	
Error	Bool	
lenRead	UInt	
onOff	UInt	
xMin	Real	
xMax	Real	
yMin	Real	
yMax	Real	
event	Byte	

**Sourcecode:**

```

#onOff := 1; // Activate Window 1
#event := 1; // Acknowledgement for indices 11, 12, 13,14

#xMin := 1.5; // Xmin coordinate of window 1
#xMax := 3.0; // Xmax coordinate of window 1
#yMin := 2.5; // Ymin coordinate of window 1
#yMax := 4.0; // Ymax coordinate of window 1

#data[0] := 0; // Byte 0 of slot number to access

```

```

#data[1] := 39;           // Byte 1 of slot number to access

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 1,         // Index 1: Slot number for indirect addressing
    LEN := 2,           // Length of data to write
    DONE => #Done,     // Write done
    BUSY => #Busy,     // Write not completed yet
    ERROR => #Error,   // Error
    STATUS => #Status, // State
    RECORD := #data);  // Write the the slot number that must be accessed
UNTIL NOT #Busy AND #Done
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
  RETURN;
END_IF;

REPEAT
  "RDREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID of Slot 1 (see introduction of 'Further examples')
    INDEX := 1,         // Index 1
    MLEN := 2,          // Max. lenth of data to read
    VALID => #Valid,    // New Data Received and valid
    BUSY => #Busy,     // Read not completed yet
    ERROR => #Error,   // Error
    STATUS => #Status, // State
    LEN => #lenRead,   // Number of bytes was read from device
    RECORD := #data);  // Read the current slot number from DIGIFORCE® 9311
UNTIL NOT #Busy AND #data[1] <> 0 AND #data[0] <> 39 // Wait till the DIGIFORCE® 9311 confirmed the slot
number
END_REPEAT;

IF #Error = TRUE OR SHR(IN := #Status, N := 24) <> 0 THEN // Check Status and Error
  RETURN;
END_IF;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 10,        // Index 10: switch on window 1
    LEN := 2,           // Length of UINT16
    DONE => #Done,     // Write done
    BUSY => #Busy,     // Write not completed yet
    ERROR => #Error,   // Error
    STATUS => #Status, // State
    RECORD := #onOff);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
  "WRREC_DB"(REQ := TRUE,
    ID := 281,           // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
    INDEX := 11,        // Index 11: Window 1 limit Xmin
    LEN := 4,           // Length of UINT16
    DONE => #Done,     // Write done
    BUSY => #Busy,     // Write not completed yet

```

```

        ERROR => #Error,           // Error
        STATUS => #Status,         // State
        RECORD := #xMin);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
    "WRREC_DB"(REQ := TRUE,
        ID := 281,                 // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
        INDEX := 12,              // Index 12: Window 1 limit Xmax
        LEN := 4,                 // Length of Real
        DONE => #Done,            // Write done
        BUSY => #Busy,            // Write not completed yet
        ERROR => #Error,          // Error
        STATUS => #Status,        // State
        RECORD := #xMax);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
    "WRREC_DB"(REQ := TRUE,
        ID := 281,                 // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
        INDEX := 13,              // Index 13: Window 1 limit Ymin
        LEN := 4,                 // Length of Real
        DONE => #Done,            // Write done
        BUSY => #Busy,            // Write not completed yet
        ERROR => #Error,          // Error
        STATUS => #Status,        // State
        RECORD := #yMin);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
    "WRREC_DB"(REQ := TRUE,
        ID := 281,                 // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
        INDEX := 14,              // Index 14: Window 1 limit Ymax
        LEN := 4,                 // Length of Real
        DONE => #Done,            // Write done
        BUSY => #Busy,            // Write not completed yet
        ERROR => #Error,          // Error
        STATUS => #Status,        // State
        RECORD := #yMax);
UNTIL NOT #Busy AND #Done
END_REPEAT;

REPEAT
    "WRREC_DB"(REQ := TRUE,
        ID := 281,                 // HW-ID for Evaluation Window 1 (see introduction of 'Further examples')
        INDEX := 15,              // Index 15: adopt values entered into indices 11, 12, 13,14
        LEN := 1,                 // Length of Real
        DONE => #Done,            // Write done
        BUSY => #Busy,            // Write not completed yet
        ERROR => #Error,          // Error
        STATUS => #Status,        // State
        RECORD := #event);
UNTIL NOT #Busy AND #Done
END_REPEAT;

```